

Optimal Multiple-Steps Single-Tuned Harmonic Filters Under Time-Varying Conditions

Ramani Kannan

Member, IEEE

Universiti Teknologi

PETRONAS,

Malaysia

kreee82@gmail.com

S. H. E. Abdel Aleem

Member, IEEE

15th of May Higher

Institute of

Engineering,

Cairo, Egypt

engyshady@ieee.org

A. F. Zobaa

Senior Member, IEEE

Brunel University London,

Uxbridge, Middlesex, UB8

3PH, U.K.

azobaa@ieee.org

A. M. Abdel Monem

Engineering Consultants Group,

Cairo,

Egypt

Ahmedabd_el_monem@hotmail.com

Abstract-- Nowadays, considering the time-varying nature of harmonic sources is a significant trend in the power quality studies. In this research, the optimum sizing of multiple-steps passive LC compensator for maximum power factor and minimum transmission loss for non-linear loads under time-varying conditions of background harmonic voltages, system impedance, and load impedance, is determined. The source harmonic voltages are varying in time independently of each other. The equivalent system impedance is given by varying the Thevenin impedance over a finite period. The functioning of the concerned LC filter is explained through a representative case study. Simulation results illustrate the viability of the suggested approach.

Index Terms-- Passive filters, power factor correction, power system harmonics, power quality.

I. INTRODUCTION

Nature of electric loads has been changed because of the extensive use of the electronic components like diodes, thyristors, etc. Such non-linear loads have widespread use in our life either industrial or residential or commercial applications. The use of these elements raises the harmonic distortion level in the power system to higher level affecting the different quality of power indices such as the load power factor, the transmission loss and the transmission efficiency. Usually, consumers pay attention to the case when they experience poor power factor and directly pay in cash the price of their consumption with penalties or indirectly in technical problems caused by the inefficient performance of their equipment because of the operation in a distorted non-sinusoidal environment. Accordingly, much effort has been exerted to find a suitable solution which improving the power factor and reducing the losses in the transmission system, and at the same time absorbing the harmonic injected by the different non-linear loads and preventing them from reaching and affecting the electric utilities [1]-[7].

Basically, one of the solutions used to lessen the effect of harmonic distortion is the use of the shunt capacitor. However, resonance hazards may occur between the capacitor and the system impedance. This may cause an over-voltage and excessive current which may damage the capacitor itself or may shorten the lifetime expectancy of the types of equipment or degrade the overall power factor. Therefore, the tendency to use LC compensators has been necessary to provide the loads with enough kvar required to improve the power factor, or compensates the reactive power, and reduce the system transmission loss [8]-[10].

Usually, in its simplest form, a series combination of an inductor L and capacitor C is common.

The previous solution is based on some assumptions which simplify the design scheme; however, it may give capacitor values that do not meet the manufacturer's standard. Refs. [8]-[12] present some practical considerations for the choice of such LC compensator values for different design criteria taken into account the capacitor values in the power quality markets. Most of such studies did not give a concern to the time-varying nature of the background harmonic voltages, equivalent system impedance, and load impedance, and usually deal with them as fixed values, which may give a misleading configuration for the optimal LC compensator to achieve the desired criteria of design.

Ref. [13] reviews and summarizes the time-varying nature of the power system harmonics. The model that used to find the optimal LC compensator values based on the time variation of the source harmonic voltages, equivalent system impedance and load impedance can give an actual presentation for such situation. Refs. [14]-[16] assumes a particular time-variation for the equivalent system impedance where the outcomes of the connected shunt capacitances were taken into consideration.

In this work, an approach to find the optimal size of the inductive reactance X_L and the capacitive reactance X_C of a multiple-steps single-tuned passive compensator under time-varying conditions, is presented. The optimal compensator values will be able to mitigate the time-varying background harmonic voltages which are assumed to be independent of each other. The suggested design of the multiple-steps single-tuned passive compensator considers the time-varying nature for both source and load impedance. Both the load power factor (PF) maximization and the transmission loss (TL) minimization are considered as objective functions. The IEEE Standard 18-2012 [17] based values for shunt-connected power capacitors are taken into account as non-linear constraints to give a viable and effective solution.

Finally, the operation of the concerned LC filter is described through a representative case study, primarily obtained from [18]. Simulation results illustrate the viability of the suggested approach.

II. FORMULATION OF THE PROBLEM

Fig. 1 shows the configuration of the system under study, taking into account the background voltage harmonic components, represented by V_{SK} that affects a load bus, experiencing an additional current harmonic distortion because of the non-linear loads used. I_{LK} represents the non-

linear load currents represented by the current source model, where K represents the harmonic order.

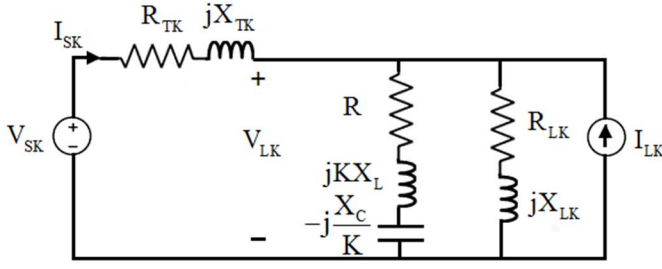


Fig. 1 Compensated time-varying non-linear load with non-sinusoidal supply

In order to derive the expressions of the K th harmonic current I_{SK} and voltage V_{LK} at the non-linear load bus (PCC), one can define the following:

- The Thevenin voltage source realizing the mains as a function of time is given as,

$$v_s(t) = \sum_K v_{SK}(t) \quad (1)$$

where t is the time in seconds and v_s is the source voltage in volts

- The K th harmonic current realizing the non-linear load as a function of time is given as

$$i_L(t) = \sum_K i_{LK}(t) \quad (2)$$

- The K th harmonic time-variant source impedance Z_{TK} is given as

$$Z_{TK} = R_{TK} + jX_{TK} \quad (3)$$

where R_{TK} and X_{TK} are the K th harmonic resistance and reactance of the harmonic Thevenin impedance, respectively. Both are given in ohms.

- The K th harmonic time-variant load impedance Z_{LK} and admittance Y_{LK} are prearranged as

$$Z_{LK} = R_{LK} + jX_{LK} \quad (4)$$

$$Y_{LK} = G_{LK} - jB_{LK} \quad (5)$$

where R_{LK} and G_{LK} are the K th harmonic load resistance in ohms and conductance in mhos, respectively. X_{LK} and B_{LK} are the K th harmonic load reactance in ohms and susceptance in siemens, respectively.

- The K th harmonic impedance of the single-tuned LC filter Z_{CK} is given as:

$$Z_{CK} = R + j \left(KX_L - \frac{X_C}{K} \right) \quad (6)$$

where R is the compensator resistance in ohms. KX_L and X_C/K represents the K th inductive and capacitive reactance of the passive filter in ohms, respectively.

Consequently, following the basic circuit analysis, one can determine the K th harmonic supply current I_{SK} and its root-mean-square (rms) value I_S in ampere, and the K th harmonic load voltage V_{LK} and its rms value V_L in volt, as follows:

$$I_{SK} = \frac{[\beta_{1K}] + j[\beta_{2K}]}{[\alpha_{1K}] + j[\alpha_{2K}]} \quad (7)$$

$$I_S = \sqrt{\sum_K I_{SK}^2} \quad (8)$$

and

$$V_{LK} = \frac{[\lambda_{1K}] + j[\lambda_{2K}]}{[\alpha_{1K}] + j[\alpha_{2K}]} \quad (9)$$

$$V_L = \sqrt{\sum_K V_{LK}^2} \quad (10)$$

where

$$A_K = R_{TK} R_{LK} - X_{LK} X_{TK},$$

$$B_K = R_{LK} X_{TK} + R_{TK} X_{LK},$$

$$X_K = KX_L - \frac{X_C}{K},$$

$$C_K = R R_{LK} - X_{LK} X_K,$$

$$D_K = R X_{LK} + R_{LK} X_K,$$

$$\beta_{1K} = V_{SK} (R + R_{LK}) + I_{LK} C_K,$$

$$\beta_{2K} = V_{SK} (X_{LK} + X_K) + I_{LK} D_K,$$

$$\lambda_{1K} = V_{SK} C_K - I_{LK} (R A_K - B_K X_K),$$

$$\lambda_{2K} = V_{SK} D_K - I_{LK} (R B_K + A_K X_K),$$

$$\alpha_{1K} = A_K - X_K (X_{LK} + X_{TK}) + R (R_{TK} + R_{LK}),$$

$$\alpha_{2K} = B_K + X_K (R_{LK} + R_{TK}) + R (X_{TK} + X_{LK}).$$

The time-varying transmission loss (TL) is given as

$$TL = \sum_K I_{SK}^2 R_{TK} \quad (11)$$

Also, the time-varying load power factor (PF) is given as

$$PF = \frac{\sum_K G_{LK} V_{LK}^2}{\sqrt{\sum_K I_{SK}^2 \sum_K V_{LK}^2}} \quad (12)$$

Equations (11) and (12) show the two objective functions. Their expressions involving the primary variables which are the parameters of the proposed compensator (R , X_L and X_C). However, before we commence analyzing the objective functions to determine the optimum size of the passive filter which achieves the two desired criteria; it is essential to define the conditions constrained them. Particularly, in this study, there are two main non-linear constraints: the resonance constraint and the operator's typical values of the shunt-connected power capacitors based on IEEE Standard 18-2012.

Regarding the resonance constraint; it determines the L and C values, or the inductive-capacitive reactance that may resonate the system. Moreover, it can be determined by equating the imaginary component of the impedance Z_{THK} seen from the load side to zero and simplifying as given in (13). Hence, solving the resulted quadratic equation; its solutions will indicate the regions of the values of X_L and X_C that should be overstepped in the selection of the filter size to prevent the occurrence of resonance.

$$\text{Im}\{Z_{\text{THK}}\}=0,$$

$$\text{Im}\left\{\frac{Z_{\text{CK}}^* Z_{\text{LK}}}{Z_{\text{CK}} + Z_{\text{LK}}} + Z_{\text{TK}}\right\}=0, \text{ or}$$

$$\begin{bmatrix} [X_{\text{TK}} + X_{\text{LK}}] \left(KX_{\text{L}} - \frac{X_{\text{C}}}{K} \right)^2 + \\ [R_{\text{LK}}^2 + X_{\text{LK}}^2 + 2X_{\text{LK}} X_{\text{TK}}] \left(KX_{\text{L}} - \frac{X_{\text{C}}}{K} \right) + \\ [R^2 X_{\text{LK}} + X_{\text{TK}} [(R + R_{\text{LK}})^2 + X_{\text{LK}}^2]] \end{bmatrix} = 0. \quad (13)$$

Regarding the typical values of the shunt-connected power capacitors; IEEE Std. 18-2012 [17] illustrates the voltage level and the corresponding standard kvar ratings Q_{Ci} of the capacitors. In this study, each value of the kvar rating Q_{Ci} of the considered voltage, that is stated in the standard, is used to determine the corresponding value of the capacitive reactance of the filter X_{Ci} , as shown in (14) and (15), respectively. Consequentially, this value is later substituted in Equation (13) to convert it into a one-variable problem with one unknown X_L . It should be mentioned that the resistance R of the filter has been neglected as the quality factor is usually considered to be high enough in the initial passive filter design [6].

$$Q_{Ci} = \{Q_{C1}, Q_{C2} \dots Q_{Cn}\}, \text{ for } i=1,2,3\dots n \quad (14)$$

where Q_{Cn} is the maximum rating (kvar) that can be used with the considered voltage. It should be noted that these kvar values are manipulated as discrete values. Hence, one can use each Q_{Ci} value to compute the resultant X_{Ci} as follows:

$$X_{Ci} = \frac{V_{S1}^2}{Q_{Ci}} \quad (15)$$

Accordingly, one can formulate the considered optimization problems as follows:

Objective function 1: Maximizing the load power factor, so that;

$$\text{Maximize } PF=f_1(X_{Ci}, X_L),$$

s.t.

$$Q_{Ci} \in \{Q_{C1}, Q_{C2} \dots Q_{Cn}\}, \text{ for } i = 1, 2, 3 \dots n$$

X_{Ci}, X_L are not a solution of (13).

Objective function 2: Minimizing the transmission loss, so that;

$$\text{Minimize } TL=f_2(X_{Ci}, X_L),$$

s.t.

$$Q_{Ci} \in \{Q_{C1}, Q_{C2} \dots Q_{Cn}\}, \text{ for } i = 1, 2, 3 \dots n$$

X_{Ci}, X_L are not a solution of (13).

III. PROBLEM SOLUTION

The two primary criteria (maximum PF and minimum TL) are considered to be independent. Therefore, equating the two differential equations formed by each criterion with respect to the variables (X_{Ci} and X_L) to zero, one can get the following:

$$\left[\frac{\partial PF}{\partial X_L} \right] dX_L + \left[\frac{\partial PF}{\partial X_C} \right] dX_C = 0 \quad (16)$$

$$\left[\frac{\partial TL}{\partial X_L} \right] dX_L + \left[\frac{\partial TL}{\partial X_C} \right] dX_C = 0 \quad (17)$$

X_C and X_L are manipulated as independent values; hence, the elements dX_C and dX_L are considered to be free or independent on each other; thus, one can reformulate (16) and (17) to become as follows:

$$\begin{aligned} \frac{\partial PF}{\partial X_L} &= 0, \\ \frac{\partial PF}{\partial X_C} &= 0. \end{aligned} \quad (18)$$

$$\begin{aligned} \frac{\partial TL}{\partial X_L} &= 0, \\ \frac{\partial TL}{\partial X_C} &= 0. \end{aligned} \quad (19)$$

The optimization approach carried out by the search algorithm is explained in the following points.

- Pick the first value of Q_{Ci} of the particular voltage, as given in Equation (14).
- Calculate the corresponding X_{Ci} , as given in Equation (15).
- Substitute the X_{Ci} value into the constraint of the resonance, given in (13), and the two objective functions.
 - Calculate the corresponding value of X_L .
 - Apply the Golden-Section algorithm to trace the local values of X_L . Such algorithm is selected due to its few steps and function evaluations.
- Let $i=i+1$, and repeat till $i=n$.
- Scan the results to find the global solution through the local solutions.
- Assess the other power quality indices and report the results.

IV. SIMULATED SYSTEM AND RESULTS

The system under study is taken from [18] for a typical power system has a 150 MVA_{SC} short-circuit strength, supply voltage of 60 Hz, 4.16 kV (2400 phase voltage). The system is serving a 5100 kW (maximum demand) and 4965 kvar three-phase loads, with a displacement power factor equals 0.765 lagging.

The notable part of the loading profile consists of induction motors; this affects the means of the cumulative distributions of the K th harmonic load impedance. Also, other loads exist such as configurations of some transformers and various lamp categories (incandescent and discharge).

Besides, it is intended that the number of loads stimulated is steadily decreasing with time during the time period T [15]. The case under study was prepared under the latter harmonic backgrounds:

- *Source harmonic voltages:*

The background harmonic voltages are alternating in time independently. The harmonic supply voltages are arbitrarily given as 5% at $K=5$, or $V_{S5}=5\%$, 3% at $K=7$, or $V_{S7}=3\%$, 2% at $K=11$, or $V_{S11}=2\%$, and 1% at $K=13$, or $V_{S13}=1\%$ [19].

Fig. 2 illustrates the K th harmonic of the mains versus the normalized time (t/T) where t is the time, and T is the period.

- *Non-linear load harmonic currents*

The load current contains a fifth harmonic current of 33 amperes, a seventh harmonic current of 25 amperes, an eleventh harmonic current of 8 amperes, and a thirteenth harmonic current of 9 amperes, as randomly chosen [16].

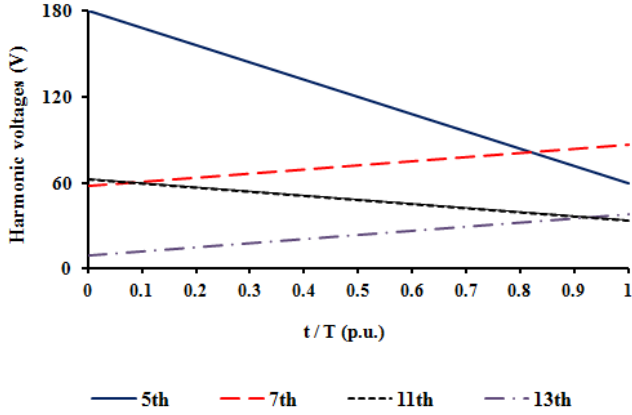


Fig. 2 Background harmonic voltages versus normalized time

- *Load impedance (Z_{LK}):*

Both load resistance and reactance are assumed time-varying values as given in Figs. 3-5, respectively.

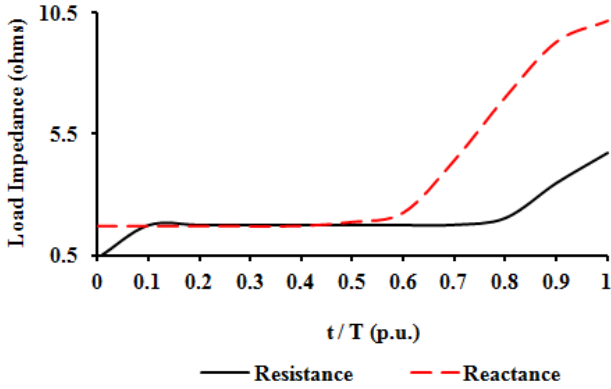


Fig. 3 Equivalent load impedance at fundamental harmonic order

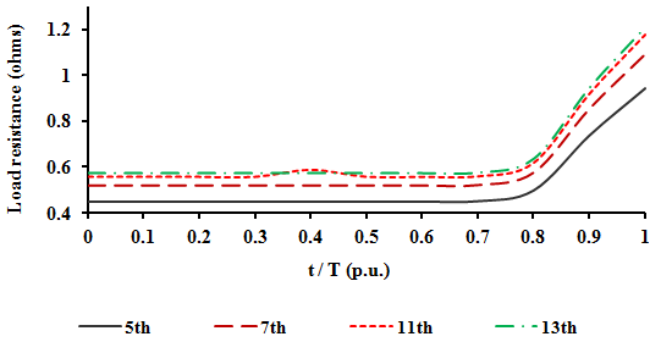


Fig. 4 The Kth equivalent load resistance

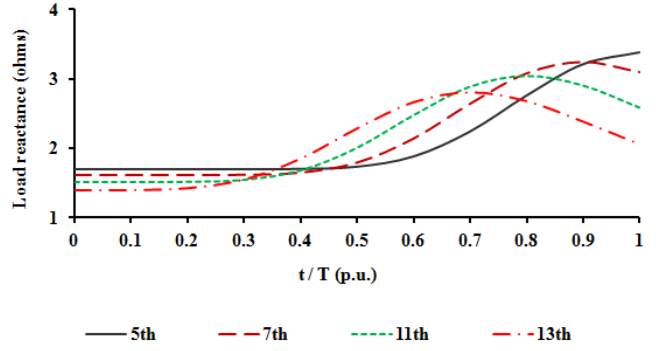


Fig. 5 The Kth equivalent load reactance

- *Equivalent source (Thevenin) impedance:*

Equivalent Thevenin impedance is assumed where the resistance R_{TK} and reactance X_{TK} are clarified in Figs. 6-8, respectively [15], so that

$$R_{TK} = R_{T1} = 0.01154, X_{T1} = 10R_{T1} = 0.1154, \\ X_{TK} = KX_{T1} \left[1 + b \left(\left(\frac{t}{T} \right)^2 - 0.25 \right) \right]. \quad (20)$$

where b is a control variable that ranges from 0 to 1 [15].

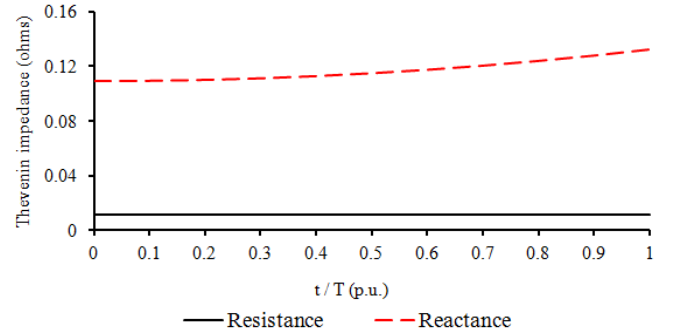


Fig. 6 Equivalent Thevenin impedance at fundamental harmonic order

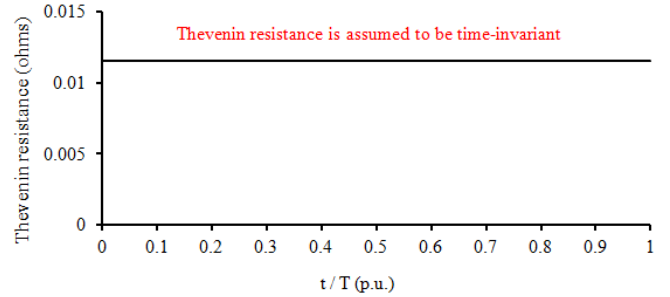


Fig. 7 The pattern of the Kth equivalent Thevenin resistance

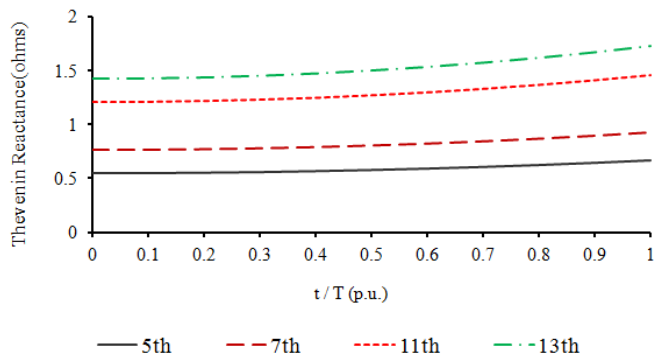


Fig. 8 The pattern of the K th equivalent Thevenin reactance

Results

The refined method is applied to the system given in Fig. 1; the exemplary arrangement is examined at discrete precise instants. Fig. 9 illustrates the pattern of the time-varying PF in per-unit for both the compensated and uncompensated systems under minimum PF criterion for various values of b .

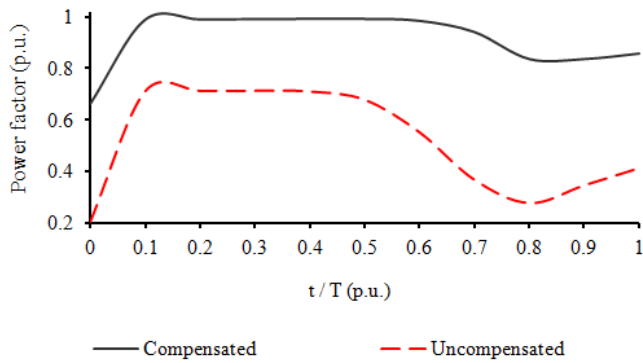


Fig. 9 PF in per-unit versus normalized time for various values of the variable b for both compensated and uncompensated systems

Figs. 10 and 11 respectively show the time variation of the load classical PF and the capacitor rating of the proposed passive filter under the effects of change of the Thevenin impedance by adjusting the value of the variable b for the same criterion.

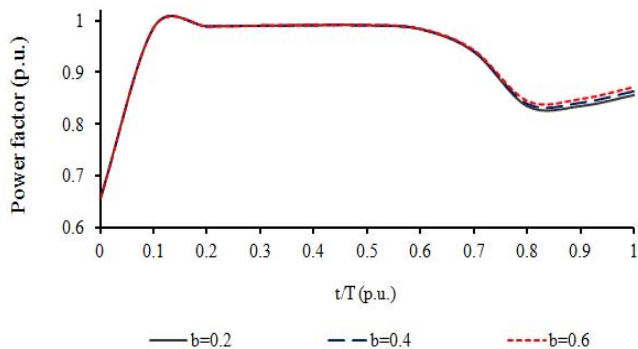


Fig. 10 PF in per-unit versus normalized time for various values of the variable b under maximum power factor criterion

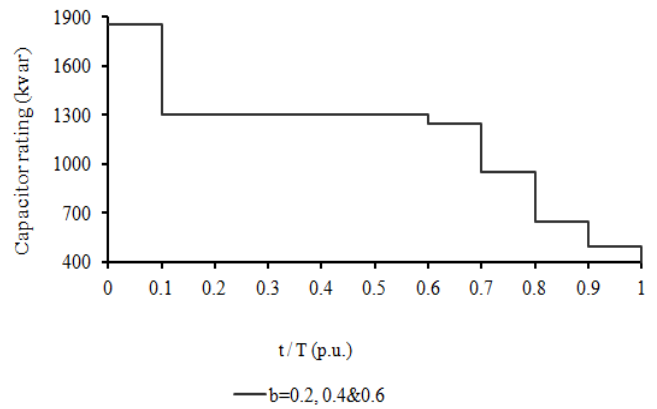


Fig. 11 Capacitor rating in kvar versus normalized time for various values of the variable b under maximum power factor criterion

Fig. 12 illustrates the pattern of the time-varying TL for both the compensated and uncompensated systems under minimum TL criterion using various b values.

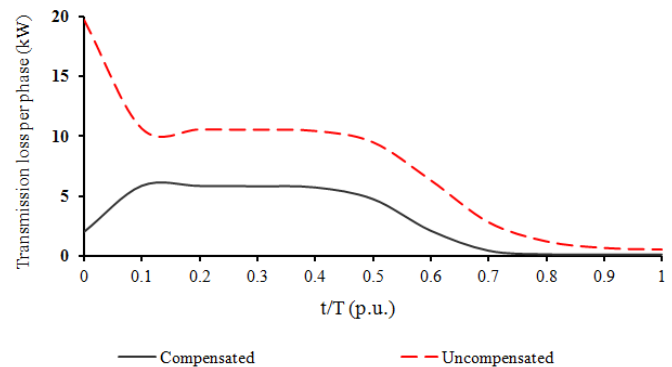


Fig. 12 TL per phase in kw versus normalized time using various b values for both compensated and uncompensated systems

Figs. 13 and 14 respectively show the time variation of the TL and the capacitor rating of the proposed passive filter under the effects of change of the Thevenin impedance by adjusting the value of the variable b for the same criterion.

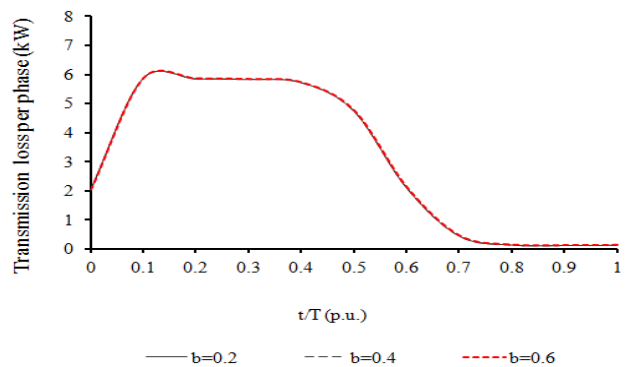


Fig. 13 TL per phase in kw versus normalized time using various b values under minimum TL criterion

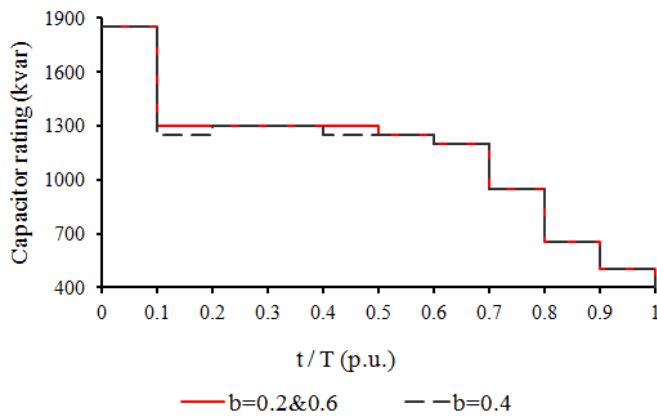


Fig. 14 Capacitor rating in kvar versus normalized time using various b values under minimum TL criterion

Finally, the previous figures have shown that the given strategy is lowering the value of the line current; thus, reducing the transmission losses and increasing the transmission efficiency, while maintaining the desired load PF at its acceptable limits ($>90\%$), compared with the corresponding simulation results without compensation [20].

V. CONCLUSION

The advance of non-linear loads has led to new challenges in the quality of power domain. Moreover, considering the time-varying nature of harmonic sources is a significant trend in the forthcoming power quality studies. In this work, the optimum sizing of multi-steps passive LC compensators for maximum power factor and minimum transmission loss for non-linear loads under time-varying conditions of background harmonic voltages, system impedance, and load impedance, is determined. The source harmonic voltages are considered varying in time independently of each other. The equivalent system impedance is given by varying the Thevenin impedance over a finite period. The functioning of the concerned filter is explained through a representative case study. Besides, the selection of the capacitor values is based on practically available (discrete) values in the markets. Simulation results illustrate the viability of the suggested approach. It is noticed the improvement occurs in the load power factor while minimizing the transmission loss and mitigating the harmonic distortion. Future works include studying the harmonic interaction phenomenon between the time-varying background harmonic voltages and the time-varying non-linear load currents. This implies adding voltage and current total harmonic distortion limits as additional constraints. Also, comparing the proposed filter design with other passive filter designs, under the same conditions, is under preparation.

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